

# **NAVIPILOT 4000**

The Self-Tuning Adaptive Heading Control System



**Sperry Marine** 

# **CONTROL AND DISPLAY UNIT**



### **SYSTEM OVERVIEW**

With the introduction of the NAVIPILOT 4000 Self-Tuning Adaptive Heading Control

**System**, Sperry Marine continues its traditional philosophy of designing autopilots with the aim of increasing profit by reducing running costs. The innovative NAVIPILOT 4000 is the first autopilot which uses steering control network technology to control a ship and is capable of tuning itself to adapt automatically to the ship's load characteristics and the prevailing weather conditions, thus reducing operational demands and increasing fuel savings and operational safety.

Conceived with the most modern computer tools in accordance with IEC 61162-3 (NMEA 2000), the NAVIPILOT 4000 permanently indicates all information required by the most stringent navigation demands:

- Current heading (digital)
- Set heading
- Override status
- Selected heading source
- Steering modes AUTO, NAV or TRACK
- · Parameters for
  - Rudder limit or
  - Rate-of-turn or radius (steering mode)
  - Weather
- Preset heading selection
- 1/10° increments of set heading

Additional Displays of:

- Load condition
- Speed (auto / man.)
- Rudder order or
- Actual rudder angle or
- Rate of turn or
- Cross track error
- Off course alarm
- Heading difference alarm

# **Sperry Marine**

# **SYSTEM CONFIGURATION**



#### **MAJOR ADVANTAGES**

- Fully self-tuning, adaptive heading control.
- Manual selection of steering strategy to suit weather conditions.
- Rate and radius control modes.
- Gyrocompass heading interfaces: two RS 422
- Magnetic compass interfaces: IEC 61162-1, sine/cosine
- Serial interface for track steering via Sperry Marine VMS or standard waypoint steering with position receivers.
- Additional remote Control and Display Units possible.
- Operational data remain stored during power failure.
- Clearly arranged graphic liquid crystal display (LCD) with back lighting.
- Logical arrangement of sealed foil keyboard and ergonomic, user-friendly operation.
- Analogue selection of set heading by means of a cardinal control disk, and soft key selection of all other major parameters.
- Analogue output for thruster control, rudder propellers and water jets.
- System utilizes the NAVINET 4000 Steering Control Network.
- Only serial digital interfaces used.
- Display and controls illuminated.
- Meets the requirements of all major classification societies.
- EC type approved by GL Luxembourg to 98/85/EC
   (Wheel Mark) Specified Standards: ISO/IEC 11674
   EN 61162-1, IEC 61162-1, EN 60945, IEC 60945
   IMO Resolutions A.342 (X), A.694 (17), A.813 (19), MSC.64
   (67) Annex 3

Bottom: Ocean Princess built by

Fincantieri for P&O

Cover: Voyager of the Seas built by

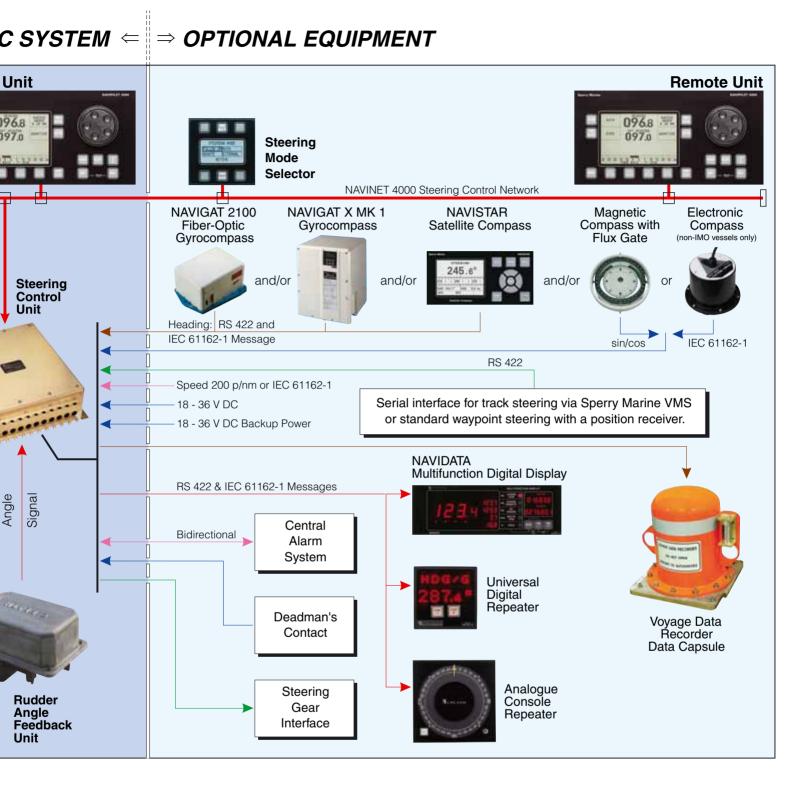
Kvaerner Masa Turku for RCCL.



# BASIC SYS



Angle Feedba



# **SUPPLEMENTARY EQUIPMENT**

#### **NAVIGAT X MK 1** Digital Gyrocompass

- Comprises one single unit.
- Microprocessor controlled.
- Easy to install and easy to service.
- Control and display unit in front cover with 4-digit heading display and 6 operating keys.
- High-speed follow-up system 100°/sec.
- Rate of turn output..
- Integrated TMC interface.
- Compass monitor function.
- Will drive a maximum of 12 analogue repeaters.

- 7 independent serial outputs RS 422 & IEC 61162-1.
- Automatic north speed error correction.
- RS 422 SUPERFAST output.
- Second gyrocompass and magnetic compass inputs.
- Complies with IMO regulations A.424(XI), A.574(14), A.821(19) High-Speed Code and ISO 8728.
- Type approved, also to the High-Speed Craft Code, in accordance with the EC Council Directive 96/98/EC.
- Rate of turn output type approved in accordance with the EC Council Directive 96/98/EC.



Watertight Housing with

156.5 mm

160 mm

1450 g

Bracket Attachment

185 mm

Height

Depth

Weight

# UNIVERSAL DIGITAL REPEATER



Environmental

 Temperature range
 -25°C to +70°C

 Vibration
 5 Hz to 50 Hz to IEC 945 / 16.5

 Protection grade
 front
 IP 65 to DIN 40050

 rear
 IP 23 to DIN 40050

 Power Requirements
 24 VDC (18 V to 36 V)

**Power Requirements** 24 V **Power Consumption** 7 W

**Type approved** in accordance with the EC Council Directive 96/98/EC.

**Signal Input** one RS 422 input with the following protocols:

 IEC 61162-1: heading gyro, heading magnetic, roll, pitch, rate of turn, X-rate, Y-rate, water speed, ground speed, transverse water speed, transverse ground speed, total/daily miles,

wind speed, wind angle, rudder angle, depth, air temperature, water temperature, time.

— C.PLATH: heading gyro, heading magnetic, rate of turn, roll, pitch.

**Dimensions and Weight** 

96 mm x 96 mm

Width

650 g

125 mm

Console Version

to DIN Standard

Front plate

Depth

Weight

Lehmkuhl: heading.

- NAVIPILOT: heading gyro, heading magnetic, set heading, speed.

Status Input Signal Output Status Output Special Feature opto-coupler, rating 24 V / 10 mA freeze mode, 180° heading change mode.

one RS 422 with protocols for the Sperry Marine Voyage Data Printer.

open collector, rating 50V/500mA. Status change according to speed input (threshold can be set in the setup menu).

Course to Steer Indicator

### **NAVIGAT 2100** Fiber-Optic Gyrocompass

- No moving parts.
- Solid-state technology.
- No maintenance during service life.
- High dynamic accuracy.
- Short settling time.
- Heading, roll, pitch and rate sensor.
- Meets all IMO recommendations including high-speed code.
- Data transmission by serial interface.
- IEC 61162-1 FAST & IEC 61161-2 SUPERFAST outputs.
- Second gyrocompass and magnetic compass inputs.

- Compass monitor and heading selector function to NAUT-AW.
- Automatic changeover to emergency power per GMDSS.
- Basic system comprises only three units: Sensor unit, Control and Display Unit and Interface and Power Supply Unit.
- Type approved, also to the High-Speed Craft Code, in accordance with the EC Council Directive 96/98/EC.
- The Rate-of-Turn output is type approved to the High-Speed Craft Code and in accordance with the EC Council Directive 96/98/EC and also fulfills IMO Resolution A.526(13)





### **JUPITER** Magnetic Compass

A "class A" compass with 180 mm card diameter for installation in NAVIPOL binnacles. Also available with a flux gate and in an overhead mounting. Type approved in accordance with the EC Council Directive 96/98/EC.

# ANALOGUE MAGNETIC COMPASS REPEATER

Magnetic compass heading console repeater with a 360° compass card. 192 mm x 192 mm. Weight 1.5 kg. Data transmission through RS 422 serial interface.



# **Steering Control Unit Control and Display Unit**

### **Sperry Marine**

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#### **Environment**

Ambient temperature range

-15° C to +55° C operation -25° C to +70° C storage

**Protection grade** 

installed IP32 to DIN 40050

**Environmental testing** to EN 60945 (IEC 945 +A1).

#### **Power requirements**

24 VDC (18 V to 36 V)

#### Max. ripple content

4 V pp, extreme values should not exceed 36 V or fall below 18 V

10 W max. **Power consumption** Reverse polarity protection built-in

Rudder angle feedback signal

 $\pm 10 \text{ V} \triangleq \pm 120^{\circ}$  max. selectable rudder angle potentiometer resistance 2 k $\Omega$ 

External steering system  $\pm 10 \text{ V} \triangleq \pm 120^{\circ} \text{ max.}$ rudder angle

## Flux gate for magnetic compass

sine/cosine, Sperry Marine product

#### **NAV/TRACK** interface

serial interface for track steering via Sperry Marine VMS or standard waypoint steering with a position receiver

**Speed input** 200 p/nm or IEC 61162-1 **180° turn command** port and starboard 180° rotation of heading display (for ferries)

Gyro / magnetic selection

Override status

Status signals AUTO, NFU, Helm, Remote, Ext. System

Set heading and rudder limit or rate or radius control by joystick or pushbutton Gyrocompass or electronic flux gate

two IEC 61162-1

Heading IEC 61162-1 HEHDT at 10 Hz Heading gyro Heading magnetic **HCHDT** or **HCHDM** or HCHDG at 10 Hz

#### Navigation system data

NSD at 1 Hz

### **Outputs**

#### DC solenoid valves

two for port Outputs

> two for starboard (solid-state relays)

Type plus or minus swiching Voltage 12 VDC to 110 VDC

Rating 2.0 A max. Additional outputs optional

#### AC solenoid valves

two for port Outputs

> two for starboard (solid-state relays)

24 VAC to 230 VAC Voltage Rating 1.0 A max.

Additional outputs optional

#### **Outputs and Interfaces**

#### CAN in accordance with IEC 61162-3

for remote control and display units

IEC 61162-1 bidirectional Central alarm

input/output

#### Voyage Data Recorder (VDR)

RS 422 9600 bps

#### Status and alarm outputs potential-free contacts

System alarm Off course alarm\* Override alarm\* Gyro / Mag. status\* Ext. system status\* Deadman's control\*

2 A maximum current 250 V maximum voltage

\* max. 4 outputs selectable

Mute\*

#### Power failure alarm

potential-free contacts Primary supply Backup supply 2 A maximum current 250 V maximum voltage

#### STEERING CONTROL UNIT

#### **Dimensions**

H 151 mm W 392 mm D 425 mm Weight 3 kg

**Cable connections** screw-down terminals Protection grade IP 32

Magnetic clearance 0.4 m

### **CONTROL AND DISPLAY UNIT**

#### Front panel dimensions

288 mm x 144 mm to DIN standard

**Installation depth** 150 mm Weight 1.5 kg

sealed foil keyboard, Front panel

illuminated

graphic liquid crystal, **Display** 

illuminated

#### Minimum magnetic clearance (installed) to

standard magnetic compass  $\leq 0.40 \text{ m}$ steering magnetic compass  $\leq 0.40 \text{ m}$ 

Sperry Marine, with worldwide headquarters in Charlottesville, VA, and major engineering and support offices in Melville, NY, New Malden, England, and Hamburg, Germany, is part of the

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